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and outputs a different motion and force. The point of a mechanism is to make the job easier to do. A parallel-motion linkage creates an identical parallel

Dijkman, e. a., motion geometry of mechanisms

Dijkman, E. A., Motion Geometry of Mechanisms. Cambridge-London-New York-Melbourne. Cambridge University Press. 1976. XVI, 288 S., 9.25

Types of kinematic joints in the design of

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A novel classification of planar four-bar linkages

as a single degree of freedom in motion) (Dijkman 1976 Dijkman, E. A. 1976 Motion geometry of mechanisms. Cambridge University Press. Dijkman,

Kinematics - wikipedia, the free encyclopedia

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Geometric and kinematic analysis of a seven-bar

bar three-fixed-pivoted compound-joint mechanism which is geometry and kinematics of the mechanisms were E.J.F. Primrose; Geared five-bar motion:

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